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Investigating the Use of Low-Discrepancy Sequences in Particle Simulations for Rarefied Gas Flows

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Overview



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- Examples of fluidic MEMS
- Simulation challenges of rarefied gas flows
- Theoretical improvements offered by low-discrepancy (LD) sequences
- Sample problem: collisionless flow in a 2D duct
- Success in low dimensions (< 100 dimensions)
- Physical explanation of poor convergence in high dimensions – particle move correlation
- Conclusions and future work



Fluidic MEMS



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Fluidic Micro-Electro-Mechanical-Systems

- Air friction in non-vacuum sealed micro-machines*
- Micro-sensors: chemical detectors, fluid monitors
- Micro patterned explosives – on chip gas generation
- Micro-thrusters – very precise satellite attitude control
- Micro-fliers – “ultimate” fly on the wall spy, and biomedical applications



* Image courtesy of Sandia National Laboratories, SUMMiT™ Technologies, www.mems.sandia.gov



Simulation Challenges



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- Fluidic MEMS often operate in the transition region between continuum and collisionless flow ($0.1 < Kn < 10$)

$$Kn = \frac{\text{mean free path between gas molecules}}{\text{length scale}}$$

- Traditional continuum and near-continuum solutions (Euler, Navier-Stokes) lose physical accuracy.
- There are insufficient molecular collisions occurring in the volume of interest for the gas to reach local thermodynamic equilibrium (LTE).
- Need to include non-equilibrium effects for an accurate simulation.



Simulation Challenges



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- Boltzmann equation: 7-dimensions $f(x_1, x_2, x_3, v_1, v_2, v_3, t)$ non-linear, integro-differential equation.

$$\frac{\partial(nf)}{\partial t} + \mathbf{v} \cdot \nabla_{\mathbf{x}}(nf) + \mathbf{g} \cdot \nabla_{\mathbf{v}}(nf) = \int_{-\infty}^{\infty} \int_0^{4\pi} n^2 (f^* f_1^* - f f_1) \mathbf{v}_r S d\Omega d\mathbf{v}_1$$

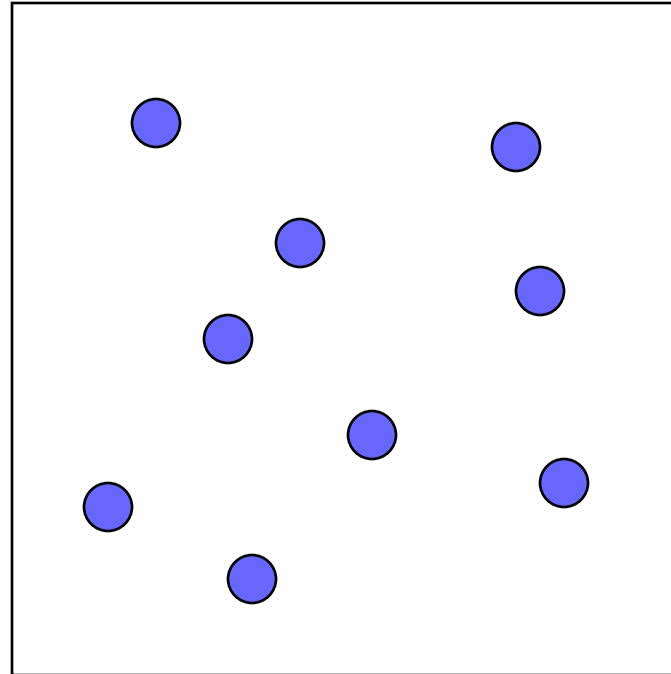
- Simulation via a direct discretization of the equation is difficult because of the memory requirements, even the simplest 1D spatial geometries require a 3D grid.
- The velocity domain is infinite.
- Direct Simulation Monte Carlo (DSMC) allows for a physically accurate non-equilibrium solution by tracking the local behavior of the gas molecules.



DSMC



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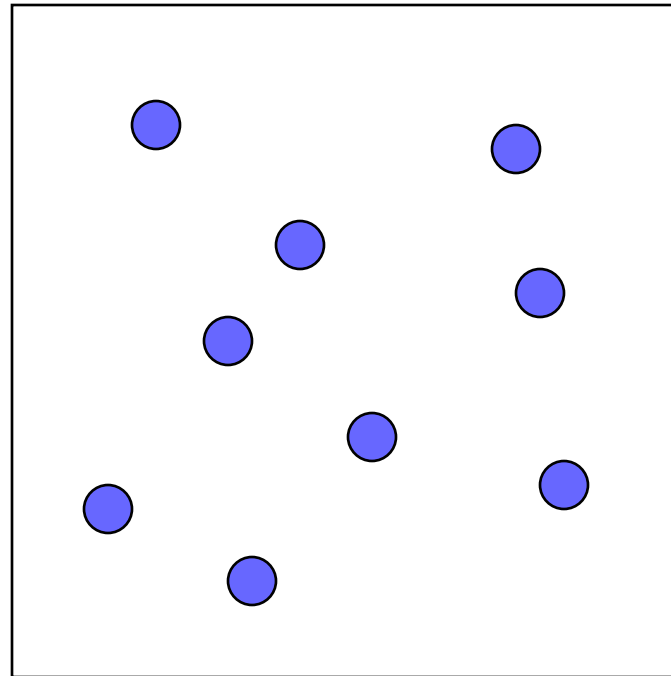
1. Choose a particle weight – in most cases there are too many physical particles (10^{20}) in the simulation domain, instead simulate a statistically valid number of sample particles.



DSMC



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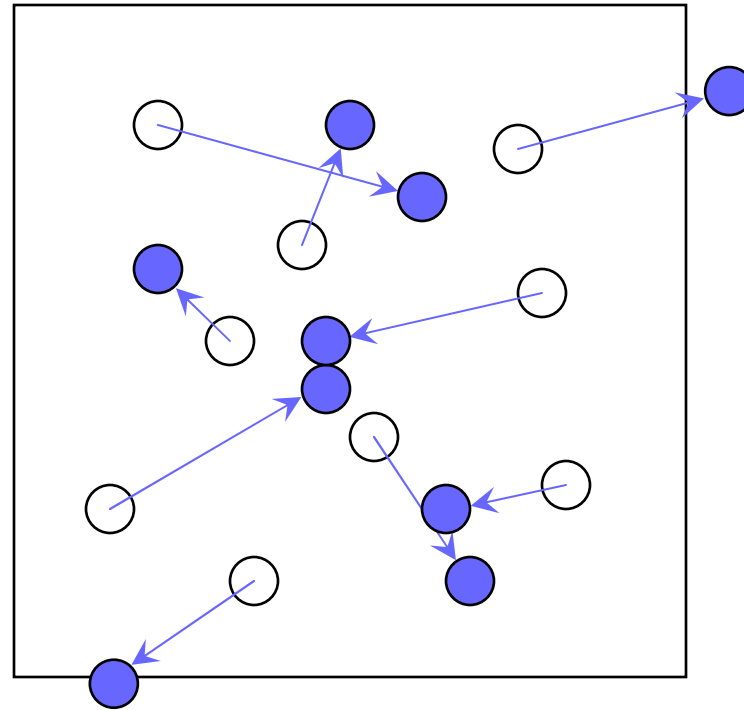
2. Choose a time step small enough so that on average only a fraction of particles undergo a collision (physics-splitting).



DSMC



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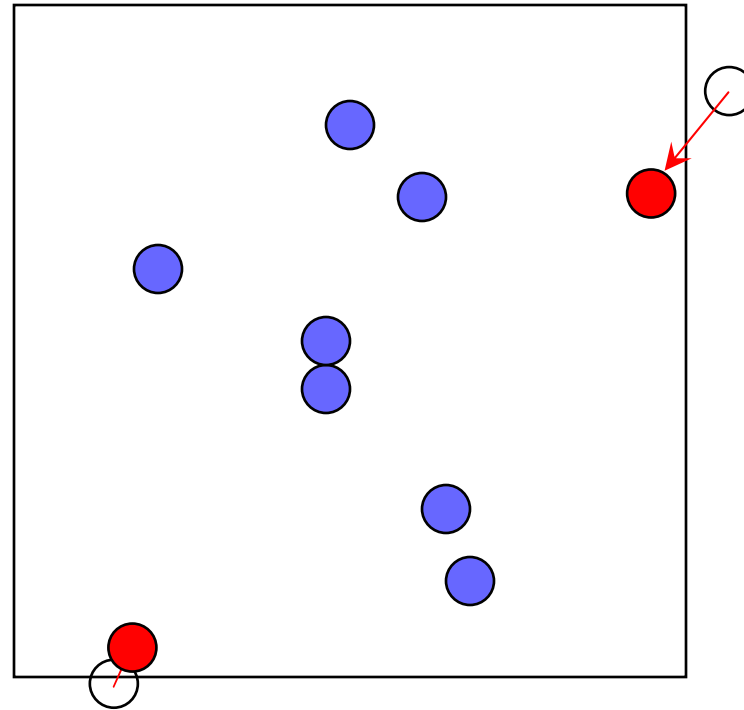
3. Move the particles based on current velocity.



DSMC



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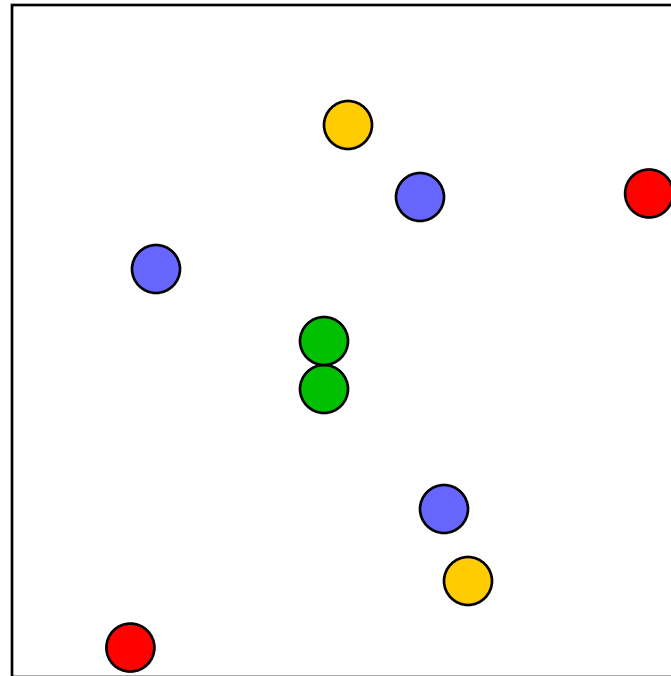
4. Find the particle-boundary interactions and select the new trajectory using the probabilistic boundary conditions and a pseudo-random number (PRN) generator.



DSMC



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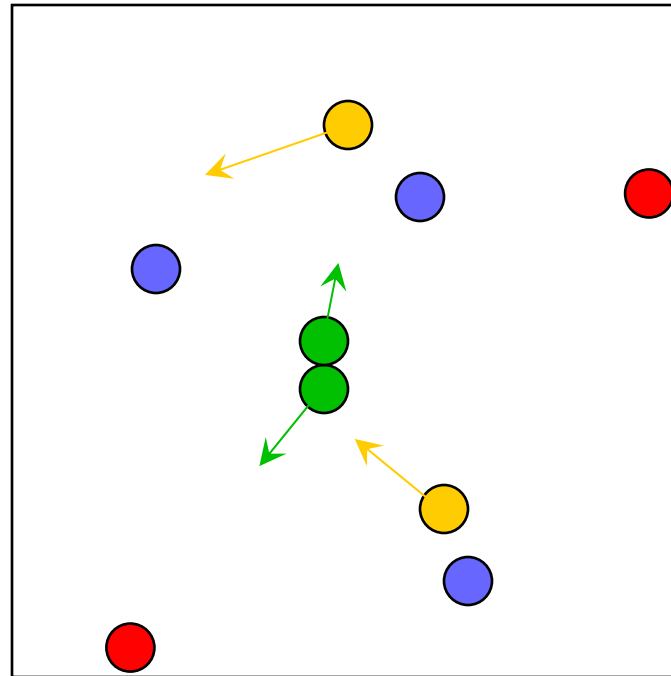
5. Calculate the number of collisions that should occur on average in the region of interest, based on the local particle density and randomly (PRN) select the collision pairs.



DSMC



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6. Sample the post collision trajectories using the PRN generator from the appropriate probabilistic description of the interaction.
7. Repeat until there are sufficient independent samples.



DSMC



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- DSMC generates sample particle behavior consistent with the Boltzmann equation without directly solving it.
- The collection of all the sample particles approximates the velocity distribution function $f(x_1, x_2, x_3, v_1, v_2, v_3, t)$ and can be used to calculate the flow properties.
- The probabilistic error bound on the method is $\sigma/N^{-1/2}$.
- For air at room temperature: $V_{avg} = 470$ m/s, $\sigma = 300$ m/s.
- The problem with fluidic MEMS simulations is that the bulk flow is often very much less than the standard deviation.
- For example: 100 mm/s accuracy requires 9M samples
10 mm/s accuracy requires 900M samples



Low Discrepancy



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- Koksma-Hlawka inequality bounds the error sampling the integrand.

$$\left| \frac{1}{N} \sum_{n=1}^N f(\mathbf{x}_n) - \int_{[0,1]^s} f(\mathbf{u}) d\mathbf{u} \right| \leq V(f) D^*(N)$$

- $V(f)$ is the bounded variation of the integrand – “smoothness”
- $D^*(N)$ is the star-discrepancy of the N -point sequence – “uniformity”
- For a Monte Carlo sequence:

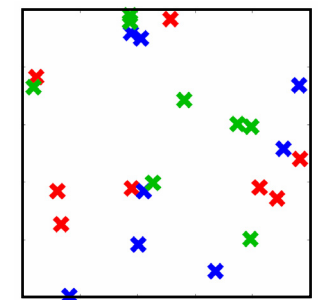
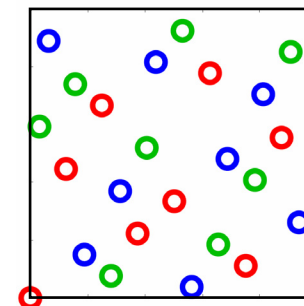
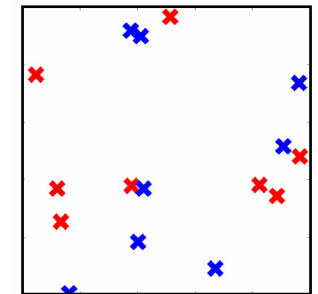
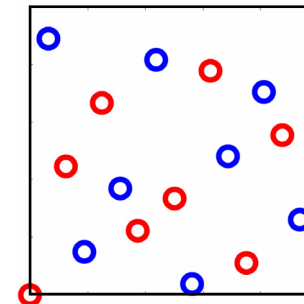
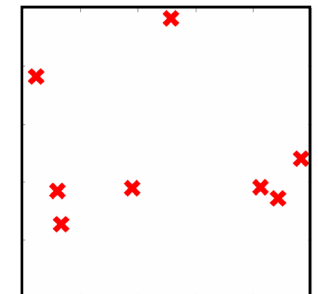
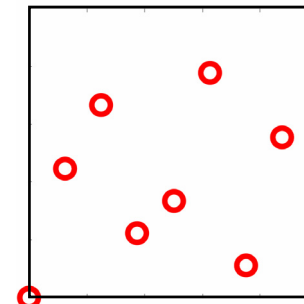
$$D^*(N) = O(N^{-1/2})$$

- For a Low-Discrepancy sequence:

$$D^*(N) = O(N^{-1} (\log N)^s)$$

Low-Discrepancy

Monte Carlo





Low Discrepancy



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- We replace the pseudo-random number (PRN) generator of the Monte Carlo method with a low-discrepancy (LD) sequence.
- The hope is that the resulting method will maintain the non-equilibrium accuracy of a particle method while achieving a near-linear convergence rate.
- Many LD sequences available:

Van der Corput, Halton, Faure

prime numbers

Richtmyer, Ramshaw

irrational fractions

Niederreiter

irreducible polynomials

Sobol'

primitive polynomials

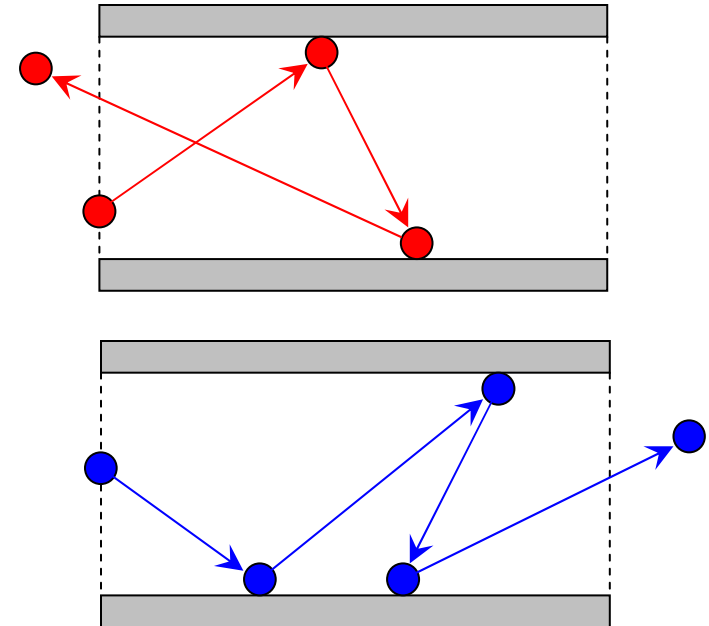


Problem Description



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- Collisionless gas flow in a 2D duct ($L = \text{length to height ratio}$).
- Only tracking particle-boundary interactions.
- Inlet – gas at equilibrium.
- Outlet – vacuum.
- Wall assumed to be fully diffuse (typical $> 90\%$) – wall reflection independent of incoming trajectory.
- Simulated quantity is the particle flow conductance which equals the fraction of particles that eventually escape the outlet from the inlet.

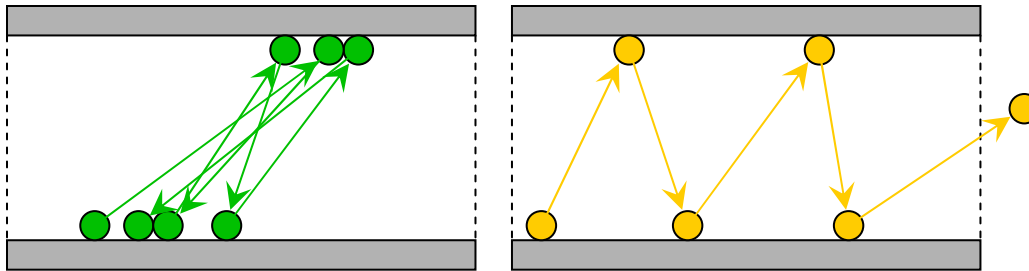




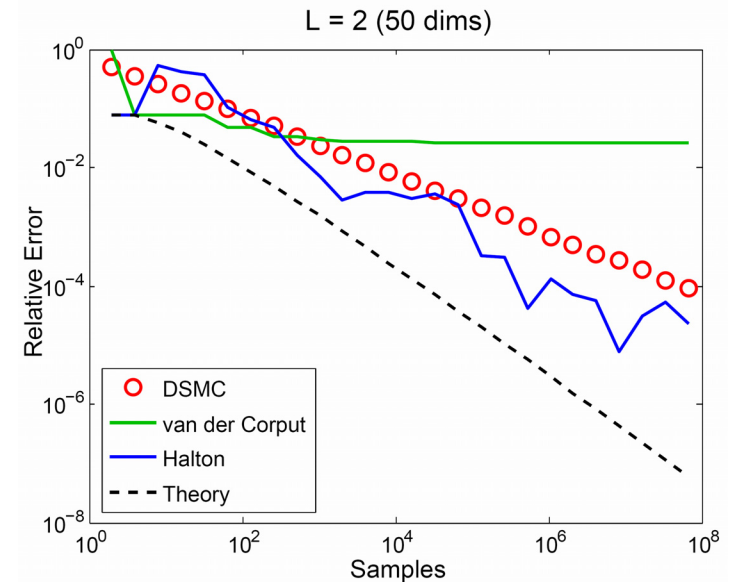
Direct Replacement



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- Replacing PRN generator with a 1D low-discrepancy sequence (van der Corput) does not converge.
- Particles move in highly correlated patterns: RLRLRLRL or RRRRLLLL.
- Instead use a multi-D, low-discrepancy sequence (Halton) with each dimension representing a particle move.
- Faster than DSMC, but does not reach theoretical rate.

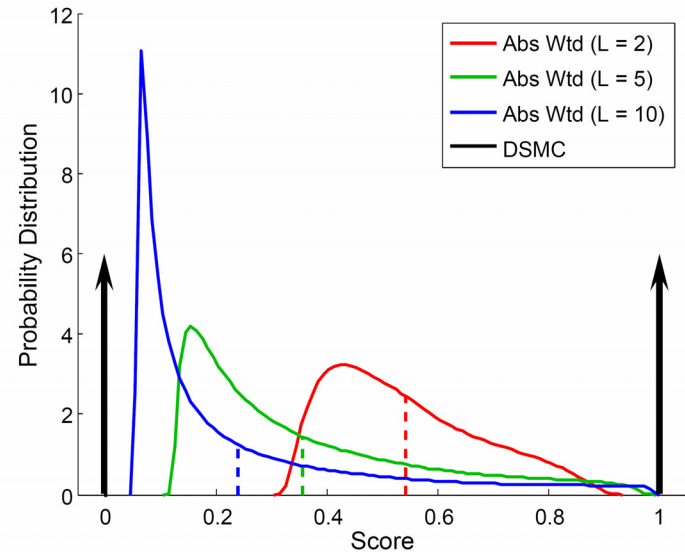
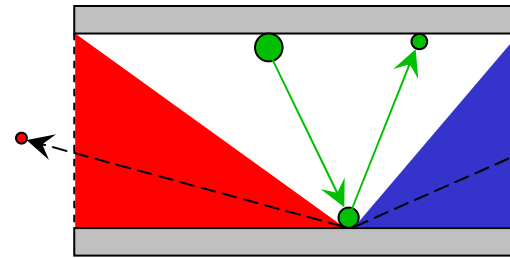
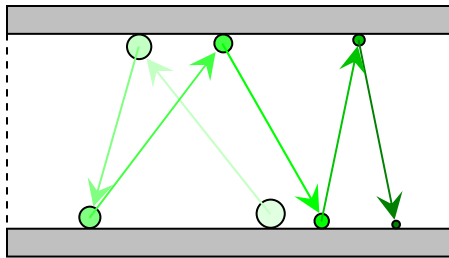




Smooth Integrand



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- The smoothness of an integrand generally affects the LD sequence performance.
- The discontinuous YES/NO decisions of the DSMC method can be avoided.
- Borrow the absorption weighting technique used for variance reduction in radiation transport problems.
- Particles no longer escape, instead the weight is reduced at each move by the fraction that should escape.

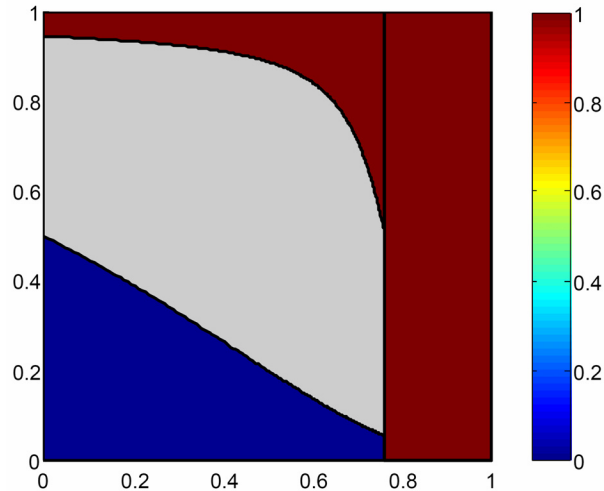


Absorption Weighting

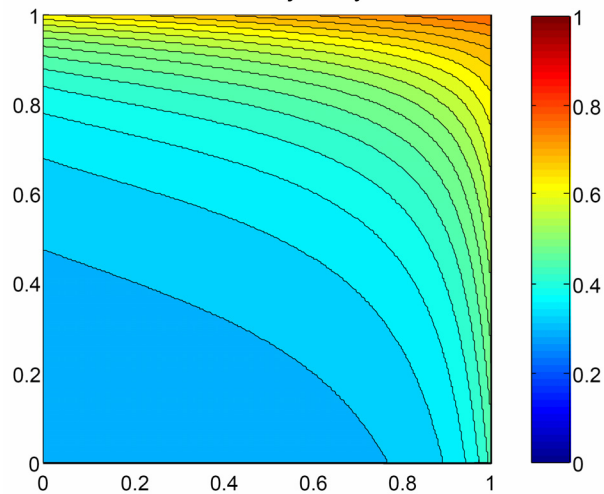


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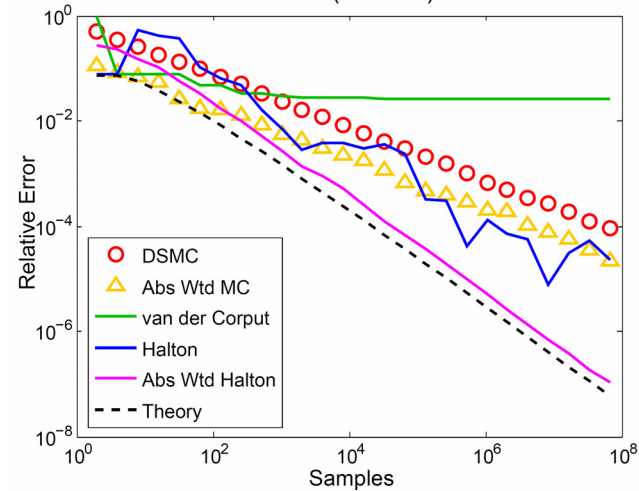
DSMC trajectory score



Abs Wtd MC trajectory score



L = 2 (50 dims)



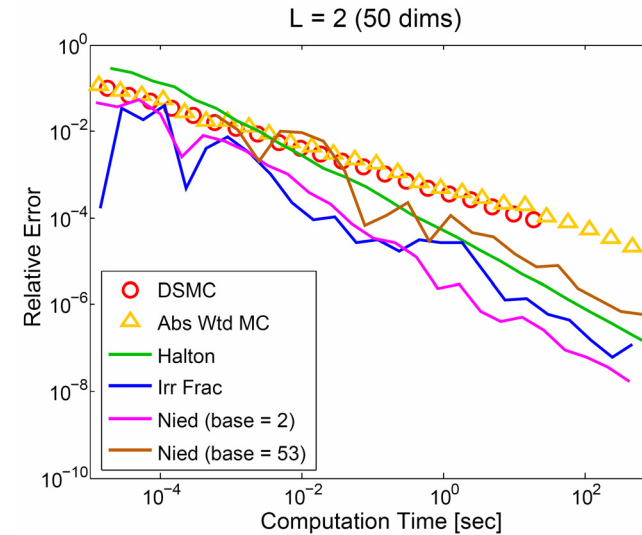
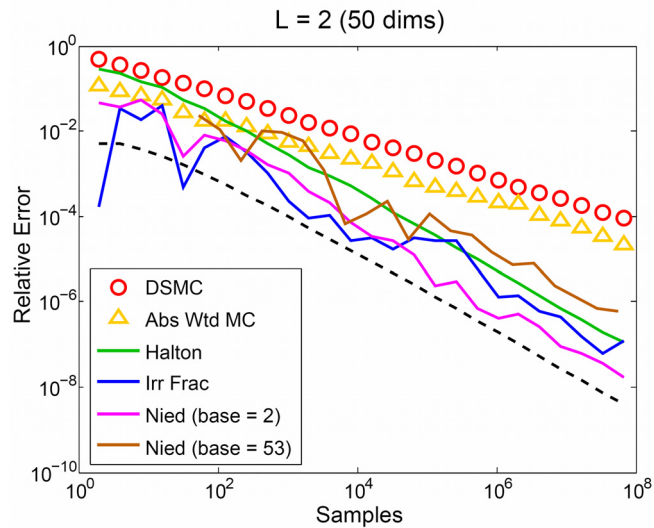
- LD performance degrades when discontinuities in the integrand are not aligned with the axes.
- The absorption weighted technique eliminates the discontinuities.
- LD sequence results in near-linear convergence.



Performance



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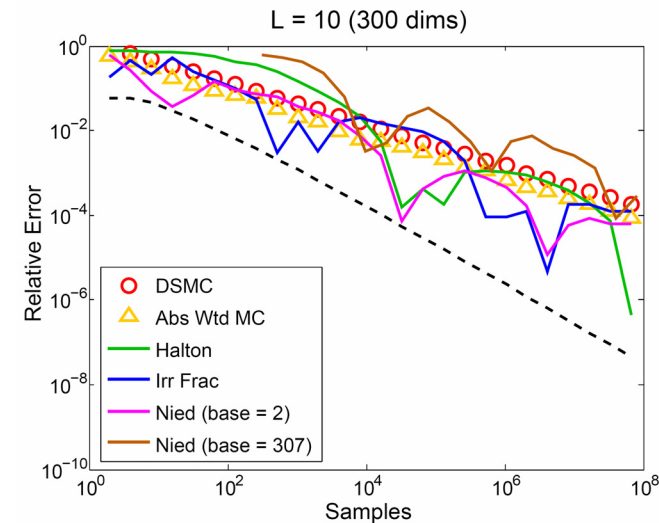
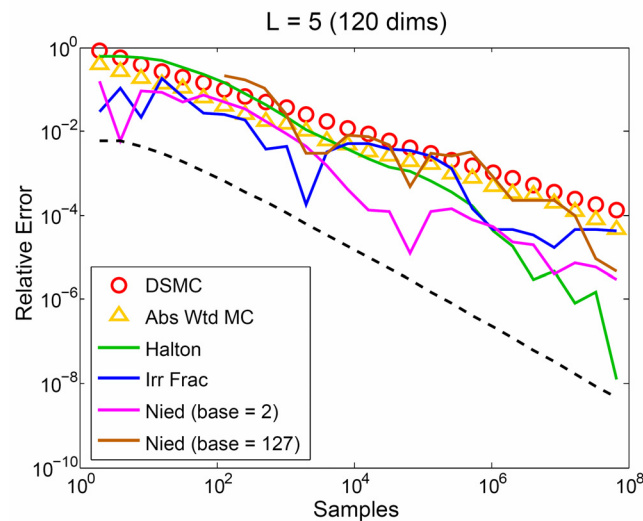
- All LD sequences eventually approach the theoretical convergence rate $O(N^{-1} (\log N)^5)$.
- Absorption weighting does lower variance but is not actually faster than direct simulation for Monte-Carlo.
- Niederreiter's sequence in base 2 consistently the fastest and most accurate.



Performance



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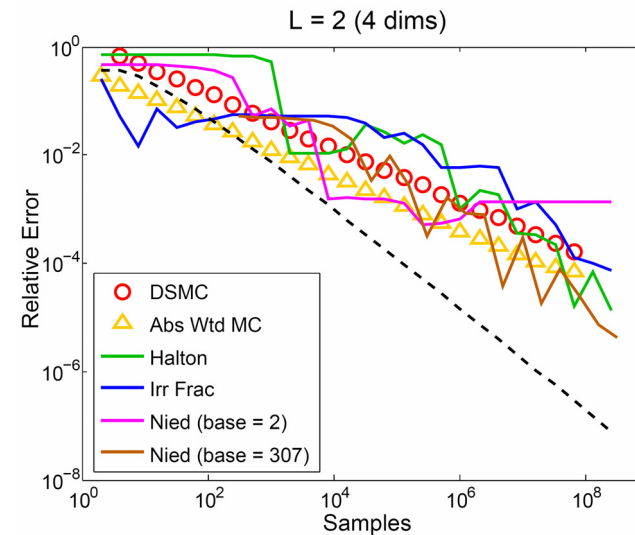
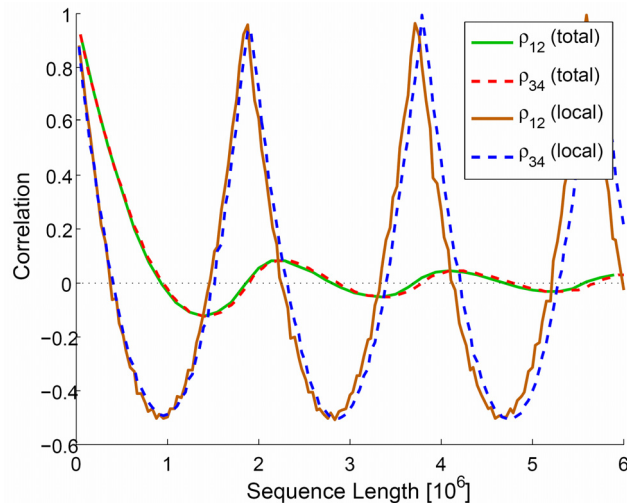
- For $L = 5$, only the Halton's and Niederreiter's sequence in base 2 show consistent gains over PRN generator.
- No sequence is clearly approaching the theoretical convergence rate.
- For $L = 10$, no sequence shows consistent improvement over PRN generator.



Correlation Problems



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- In higher dimensions, the “independent” LD generators for each dimension become more similar.
- When 2D correlation between pairs of sequences ρ_{12} and ρ_{34} is similar the resulting 4D correlation persists longer.
- Four move simulation using the most “obvious” candidates from the 300 dimensional sequences shows similar convergence to the $L = 10$ case.



Conclusions



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- It is possible to construct a simple particle simulation that achieves near linear convergence $O(N^{-1} (\log N)^s)$ using low-discrepancy sequences.
- You cannot simply replace the PRN generator in your DSMC code with a low-discrepancy one.
- When the dimension of the problem is sufficiently small ($D < 50$), significant performance gains can be achieved (350 times faster).
- In higher dimensions ($D < 120$), some low-discrepancy sequences still offer faster convergence than Monte-Carlo.
- Correlation between dimensions of the LD sequence causes the particle moves to have non-physical behavior.
- Offers potential for improving solutions for fluidic MEMS.



Future Work



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- Reduce the problem dimension:
 - + use LD sequences only on “dominant” dimensions
 - + discretize the problem and try to smooth the grid interaction
- Coupling between two probabilistic processes.
- Other variance reduction techniques.



Acknowledgements



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I would also like to thank Sandia National Laboratories, in particular, Michael Gallis, Wahid Hermina and the Engineering Sciences Center dept. 9113 for their support during my practicum.



Questions?



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“Any one who considers arithmetical methods of producing random digits is, of course, in a state of sin.”

- John von Neumann (1951)

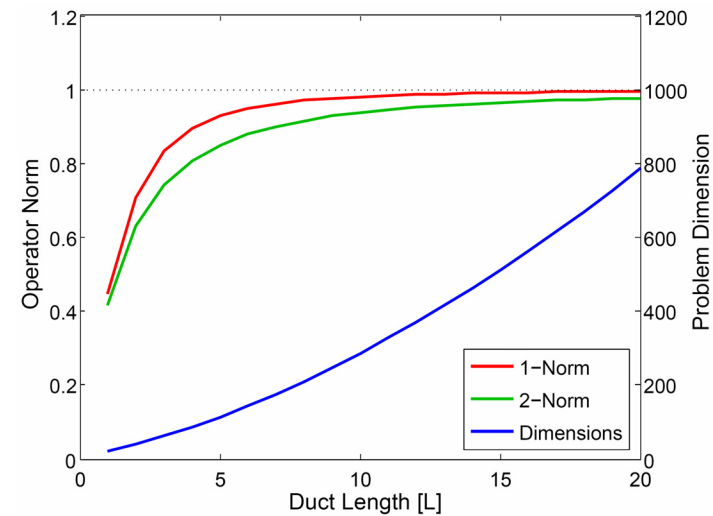
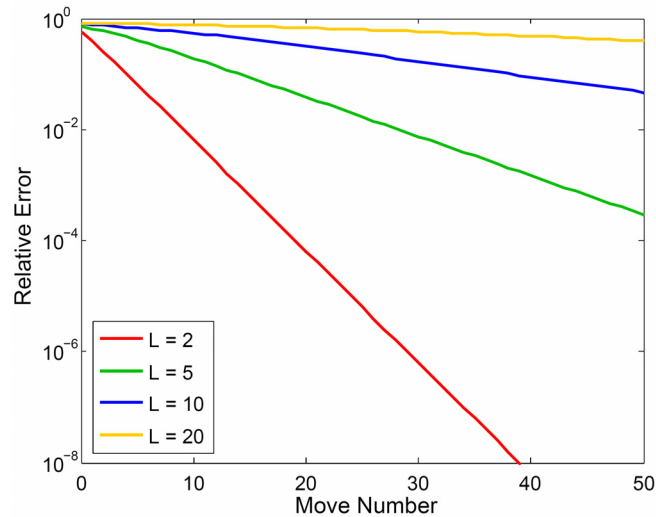
J. Von Neumann, ‘Various techniques used in connection with random digits.’ *National Bureau of Standards Applied Mathematics Series*, vol. 12, 36-38, 1951.



Increasing Dimensions



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- As duct length increases, so does the necessary number of particle moves (dimensions) to achieve a specific error.
- Physically, it means the particles are spending a longer time in the duct.
- Mathematically, the operator K governing the particle moves also governs the error $|e_{n+1}| < |K||e_n|$ and the norm approaches 1 as the duct length increases.



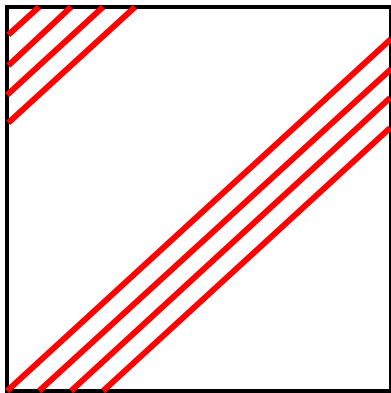
Correlation Patterns



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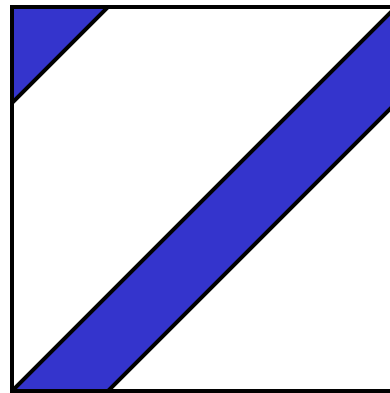
Halton

Max length: 1.8M



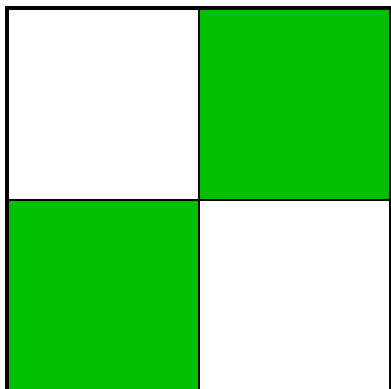
Irrational Fractions

Max length: 14M



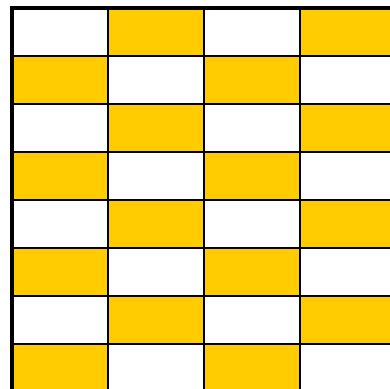
Niederreiter (base 2)

Max length: 2.1M



Niederreiter (base 2)

Max length: >2.1M



- LD sequences in high dimension can show obvious correlation patterns between dimensions.
- The resulting correlation between moves is similar to the 1D sequence.
- Correlation is not bad provided that the correlated sequence length is smaller than the total simulation.
- The “curse of dimension.”