

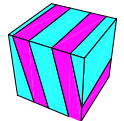
Constrained sequential lamination: a sub-grid multiscale material model

Matt Fago
GALCIT, Caltech
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Collaborators: S. Aubry (Sandia), M. Ortiz (Caltech)

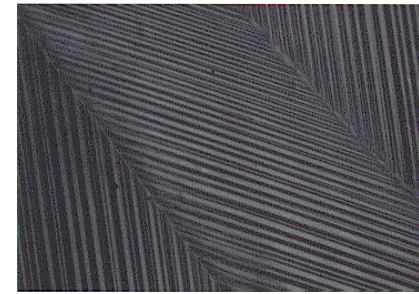
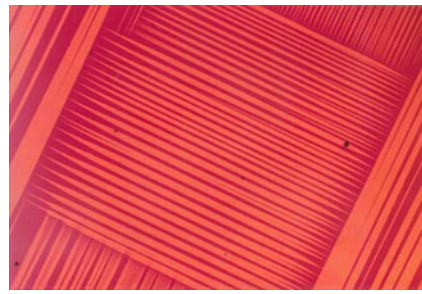
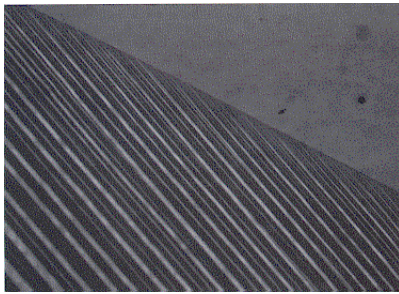
Background: Why multiscale modeling?

- Material behavior is often strongly influenced by the coupling of processes occurring over a range of length scales
- Some length scales and processes in solid mechanics
 - Angstrom -- electronic structure
 - Nanometers -- vacancies, dislocation cores
 - Microns -- dislocation interactions
 - Millimeters -- subgrain microstructure
- Multiscale methods incorporate effects from several scales
 - Build aggregate models \Rightarrow higher fidelity
 - Direct application for some problems

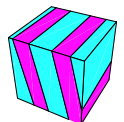


Laminate introduction

- Prediction of the development of microstructures and their effect on material behavior is a key problem in the study of martensitic materials (e.g., shape memory alloys)

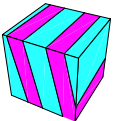


- Need an efficient numerical method for solving macroscopic boundary-value problems while simultaneously accounting for microstructure development



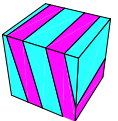
Introduction continued

- Pose problem as energy minimization
- Such materials have several variants (or phases) \Rightarrow multiwell energy density
- Direct minimization results in “unrelaxed” solution
- Energy not quasiconvex
 - Infimum not attained: develop microstructures
 - Discretization must resolve microstructural details
 - Mesh biases results



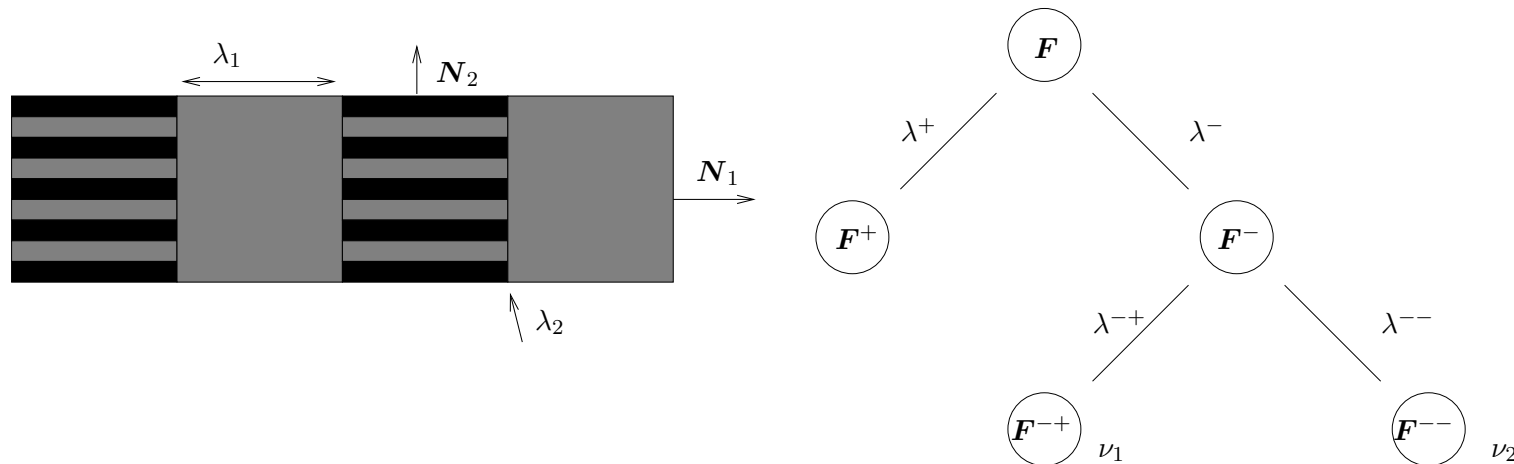
Problem formulation

- Wish to replace multiwell energy with quasiconvex envelope
 - This “relaxed” energy is well behaved
 - Require separation of length scales
 - No general algorithm is known
- Compute *partial* relaxation using the concept of sequential lamination and rank-one convexification

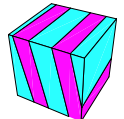


Sequential laminates

- Layered mixture of variants described by a binary tree

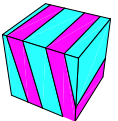


- For a given graph, material completely described by:
 - Average deformation gradient \mathbf{F}
 - Polarization, normal, proportion $\{\mathbf{a}, \mathbf{N}, \lambda\}$ and well number at each leaf



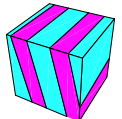
Lamination algorithm overview

- Formulate energy in terms of graph variables
- Include model of interfacial energy
 - Estimate of length scale
 - Eliminate runaway refinement
- Optimize laminate by minimizing energy with respect to:
 - Graph variables: $\{\mathbf{a}, \mathbf{N}, \lambda\}$ and well number of each leaf
 - Graph topology
- Resulting laminate is in static and configurational equilibrium



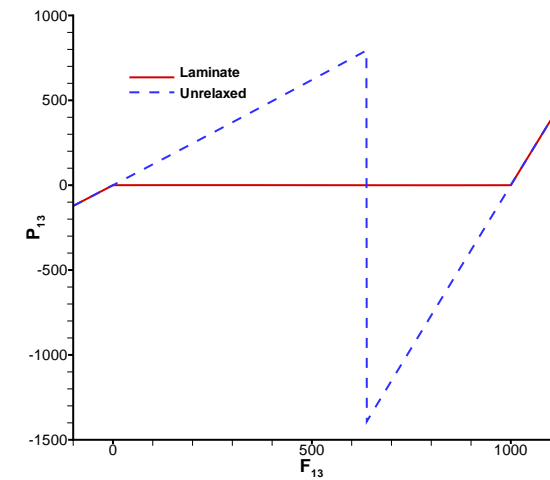
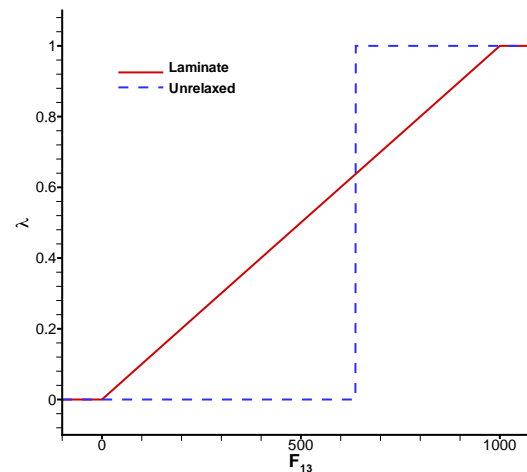
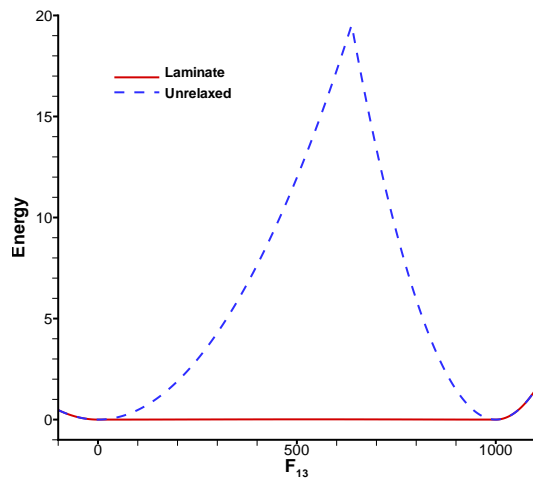
Laminate evolution

- Full rank-one convexification follows from consideration of **all** possible graphs
- Not feasible: use natural dynamics to visit important states
 - Graph must be “stable” (no zero volume fractions)
 - New graph accessible through pruning and branching
 - Prune: remove null subtrees
 - Branch: add two children if it reduces energy \Rightarrow driving force for branching
- Process of continuation: may not deliver absolute rank-one convexification, but provides a simple model of metastability and hysteresis

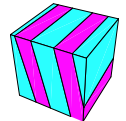


Example: martensite-martensite transition

- Load from one transformation stretch to another to illustrate simple mixing between two wells

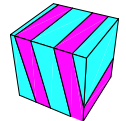
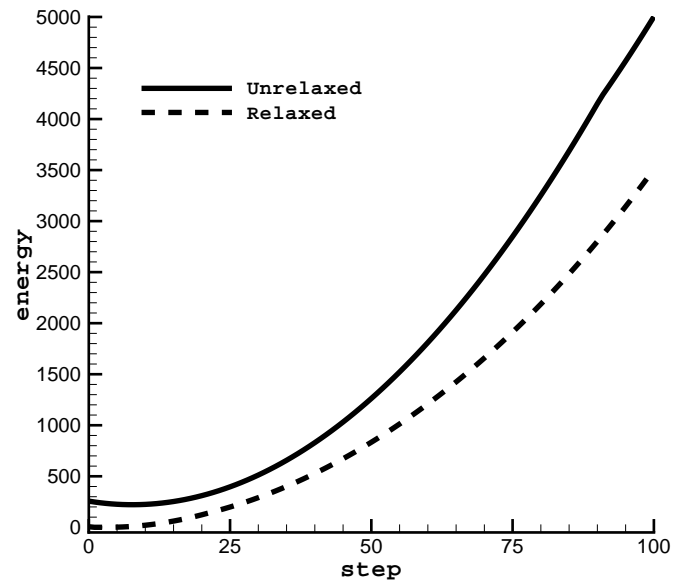
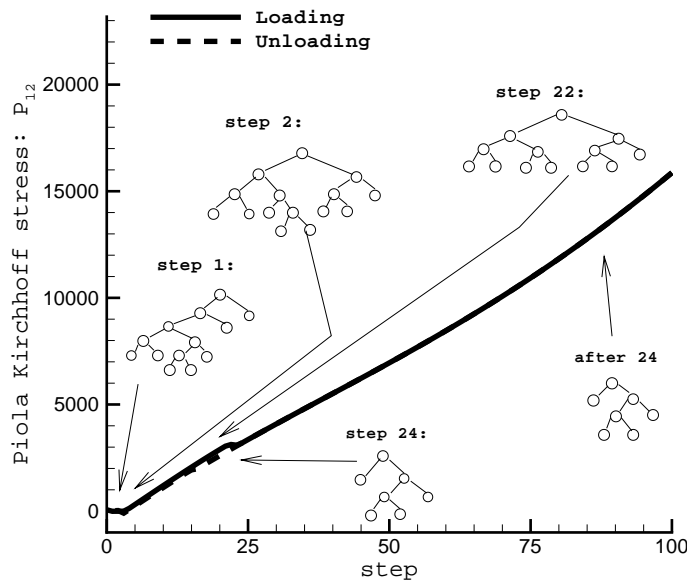


- Smooth transitions
- Fully relaxes energy and stress



Example: simple shear

- Load in simple shear
- Exclude austenitic well: forced to develop microstructure in initial configuration

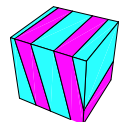
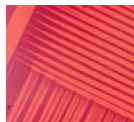
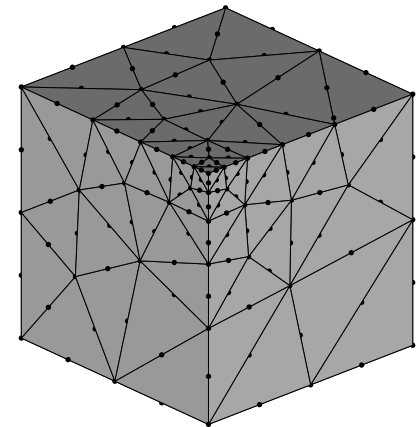


Finite element implementation

- Laminate model applied in parallel at mesh integration points providing stress and energy given deformation gradient
- Solution by energy minimization using dynamic relaxation followed by preconditioned conjugate gradient iteration

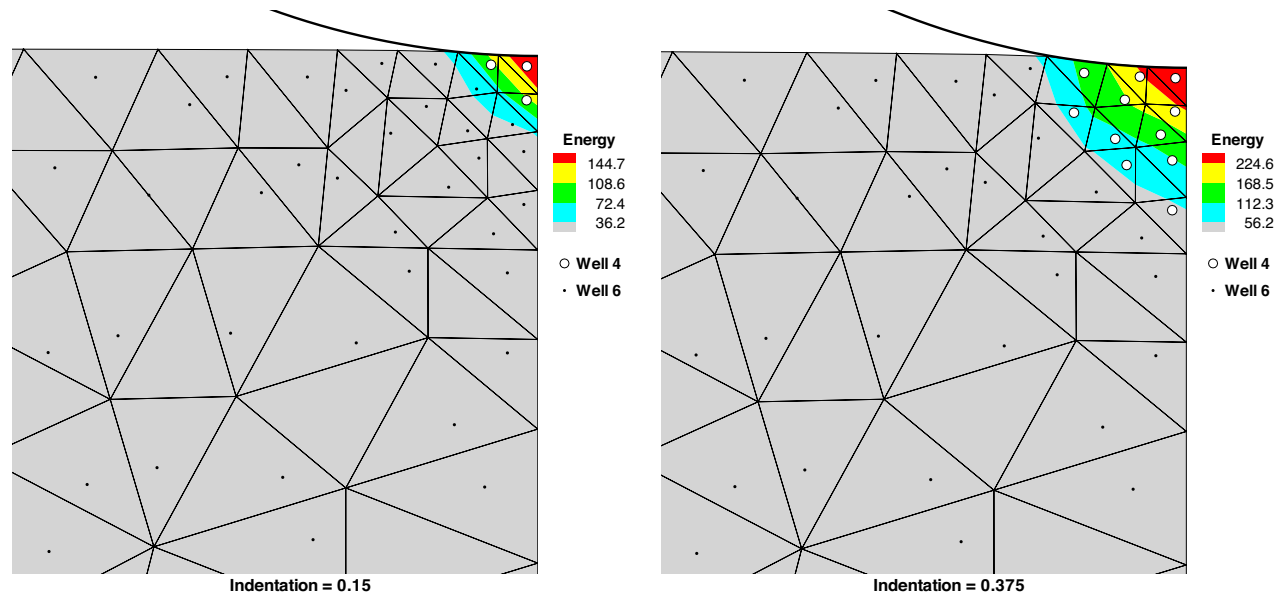
Finite Element Example Calculation

- Quasistatic indentation of Cu-Al-Ni by spherical indenter
- Quarter model of 20 mm region under a 15 mm radius indenter with 254 nodes and 105 ten-node finite strain quadratic elements
- Contact modeled by a penalty method



Finite element unrelaxed solution

- Baseline for comparison

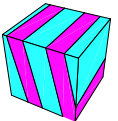


- Activate one martensitic well under indenter
- Fineness of variant arrangement limited by mesh



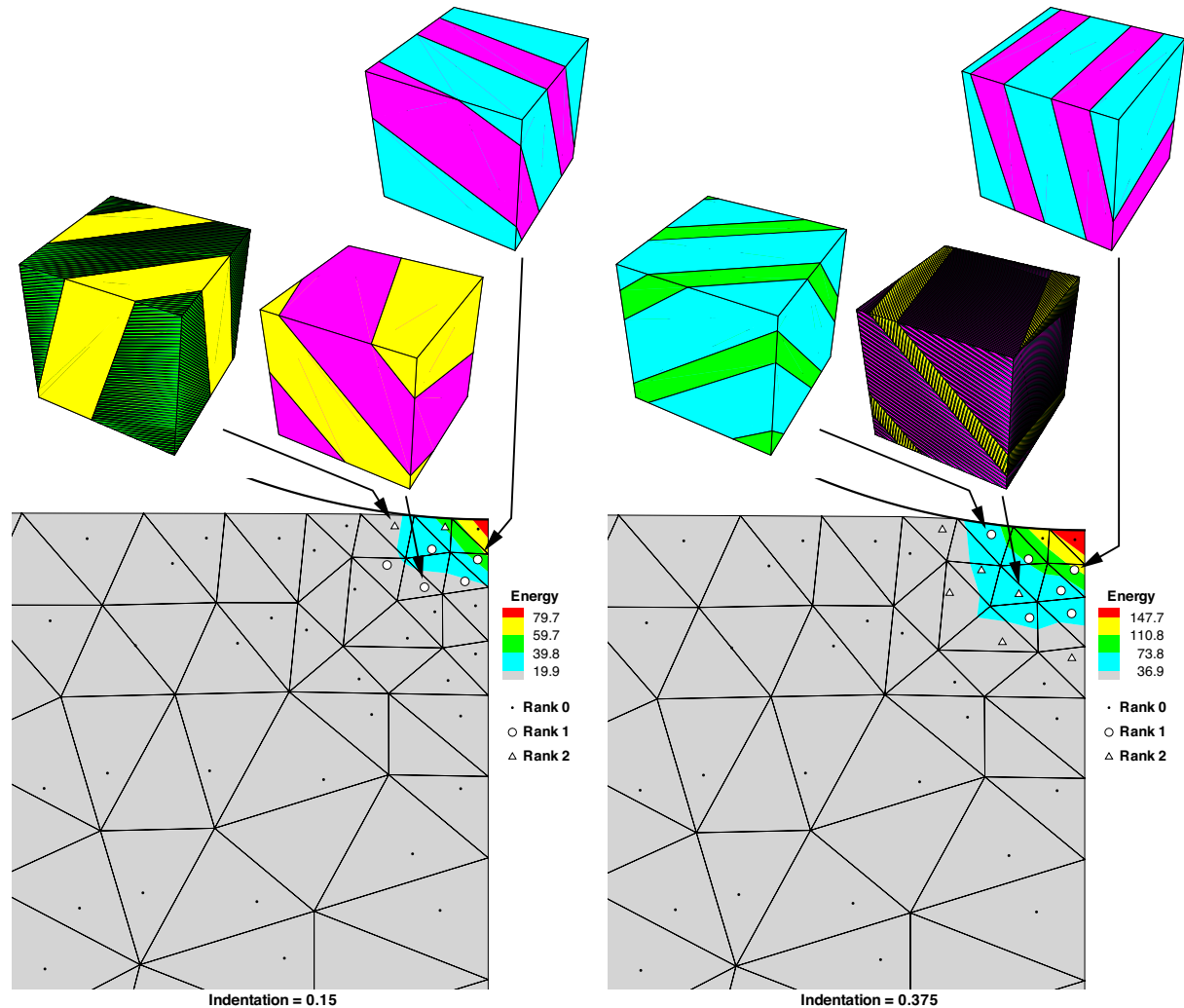
Constrained sequential lamination

Matt Fago July 16, 2003
Page 11 of 17

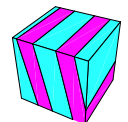


Finite element relaxed solution

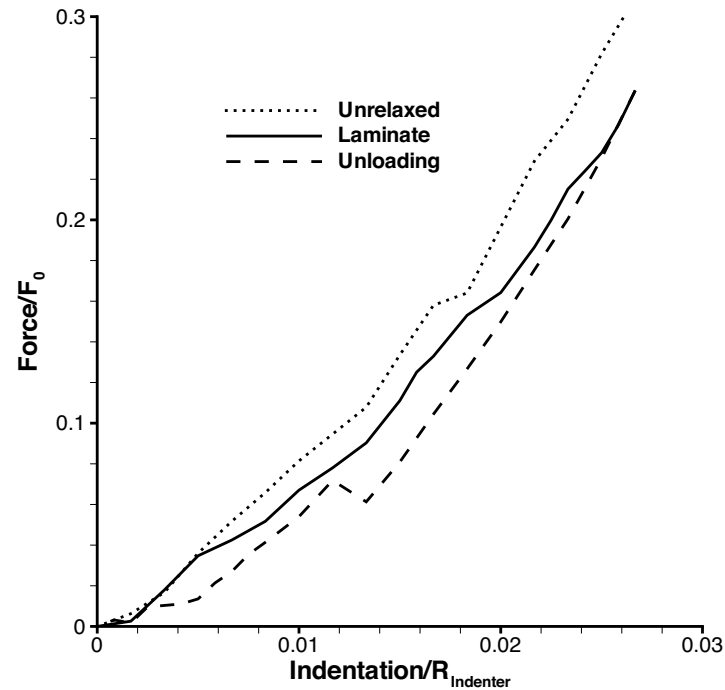
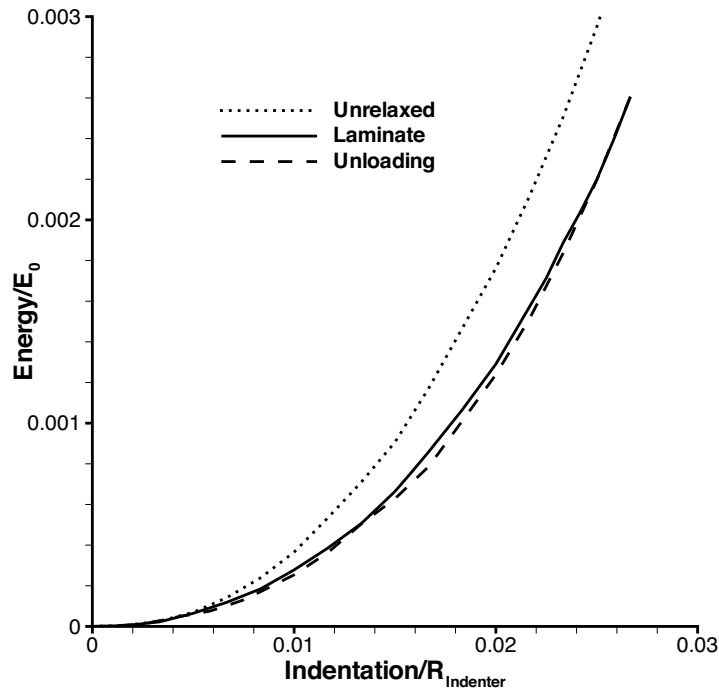
- Develop rank 1 and 2 laminates
- De-twinning observed under indenter



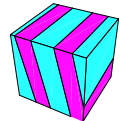
Constrained sequential lamination



Finite element results: energy & force

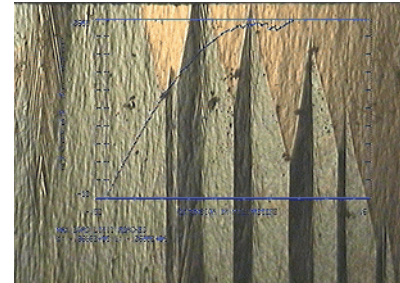
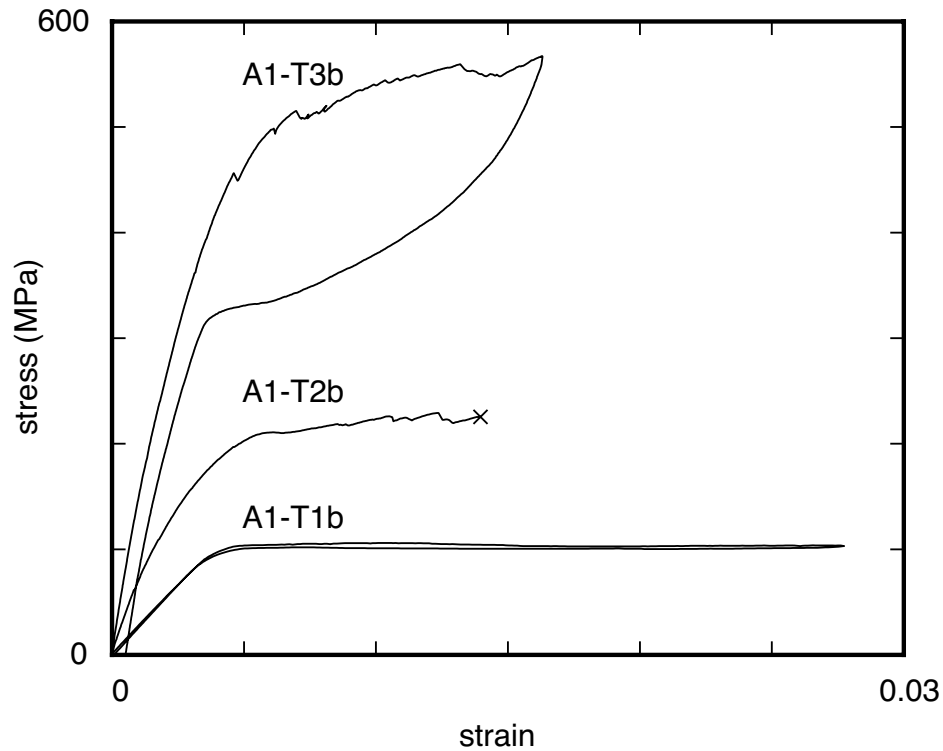


- Laminates produce softer response
- Unloading exhibits path-dependent nature of algorithm

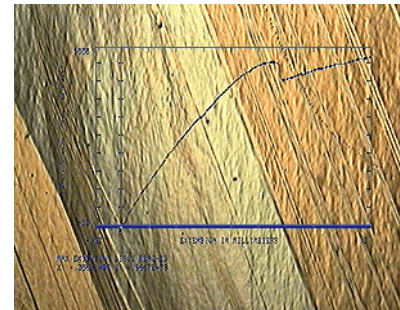


Experimental results

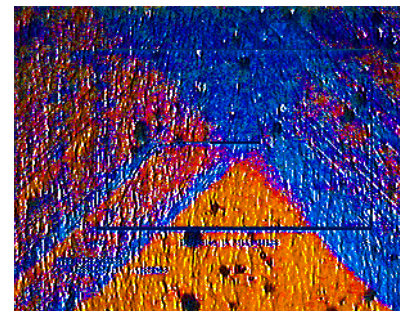
- T. Shield tension test experiments at several crystal orientations



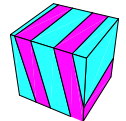
A1-T3b



A1-T2b

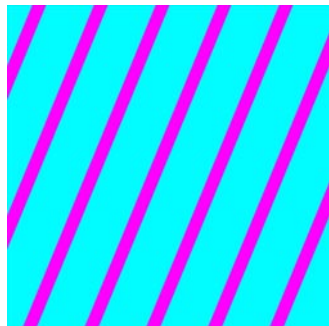


A1-T1b

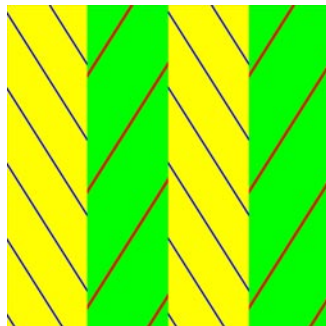


Experimental validation: single point

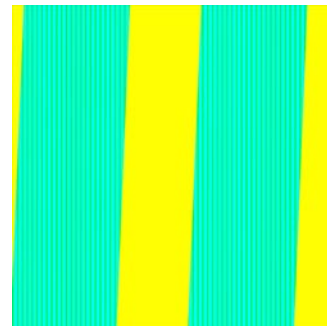
- “Single point” laminate calculations
- Sensitive to boundary conditions
- Similar microstructures obtained
- Significantly higher transformation stresses



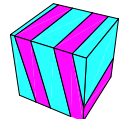
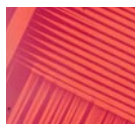
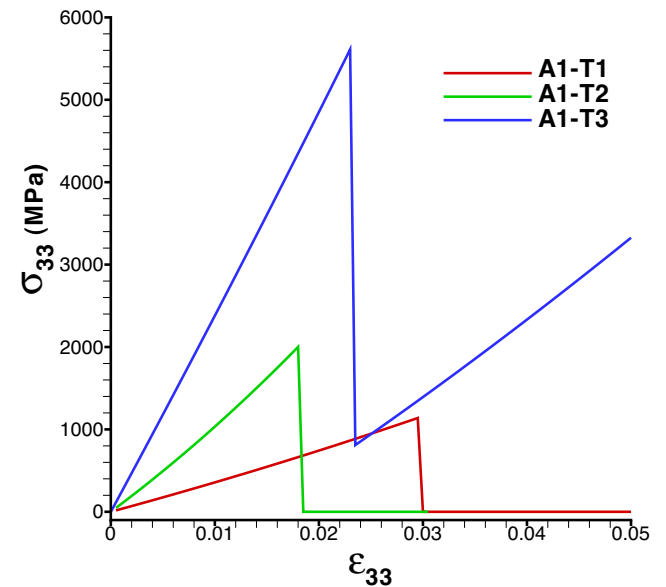
A1-T1b



A1-T2b

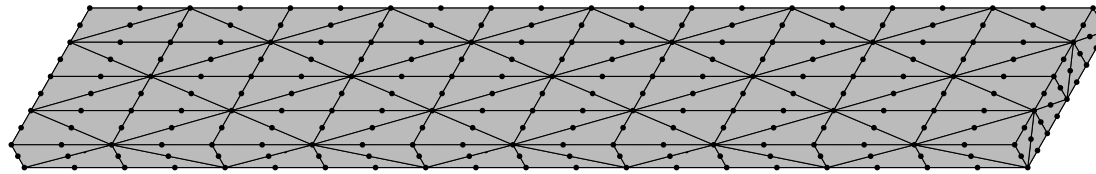


A1-T3b

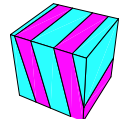
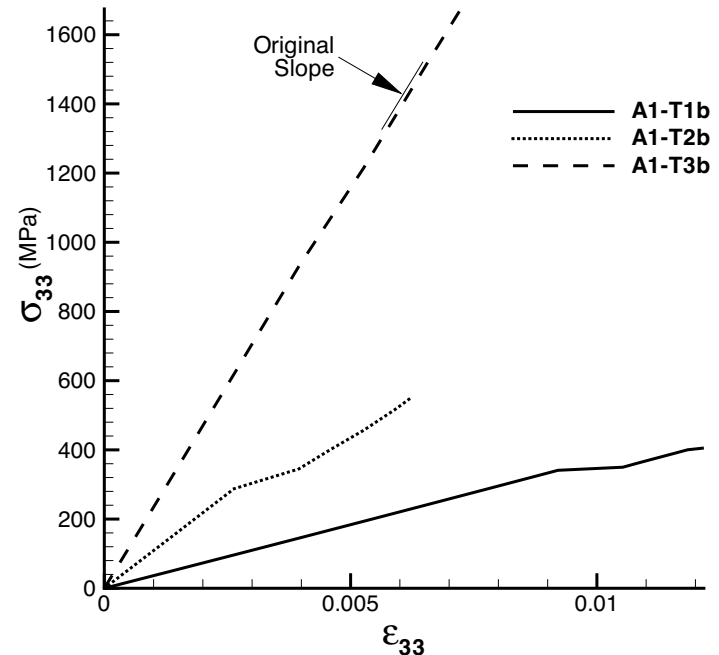


Validation: finite elements

- Finite element simulation of test specimen



- Unambiguous boundary conditions
- Reduction in transformation stress, with significant softening observed



Conclusions and future work

- Demonstrated practical algorithm for partially relaxing multiwell energies through sequential lamination
- Demonstrated application of laminate model at the subgrid level of a finite element simulation
- Model produces microstructures similar to those obtained experimentally
- Can be extended to more accurately model real materials
 - Model of nucleation to reduce transformation stress
 - Replace equilibrium with kinetic relation governing interfacial motion
 - Extend to include plasticity (add variants for each slip-system)

